



Center for Sensor Systems

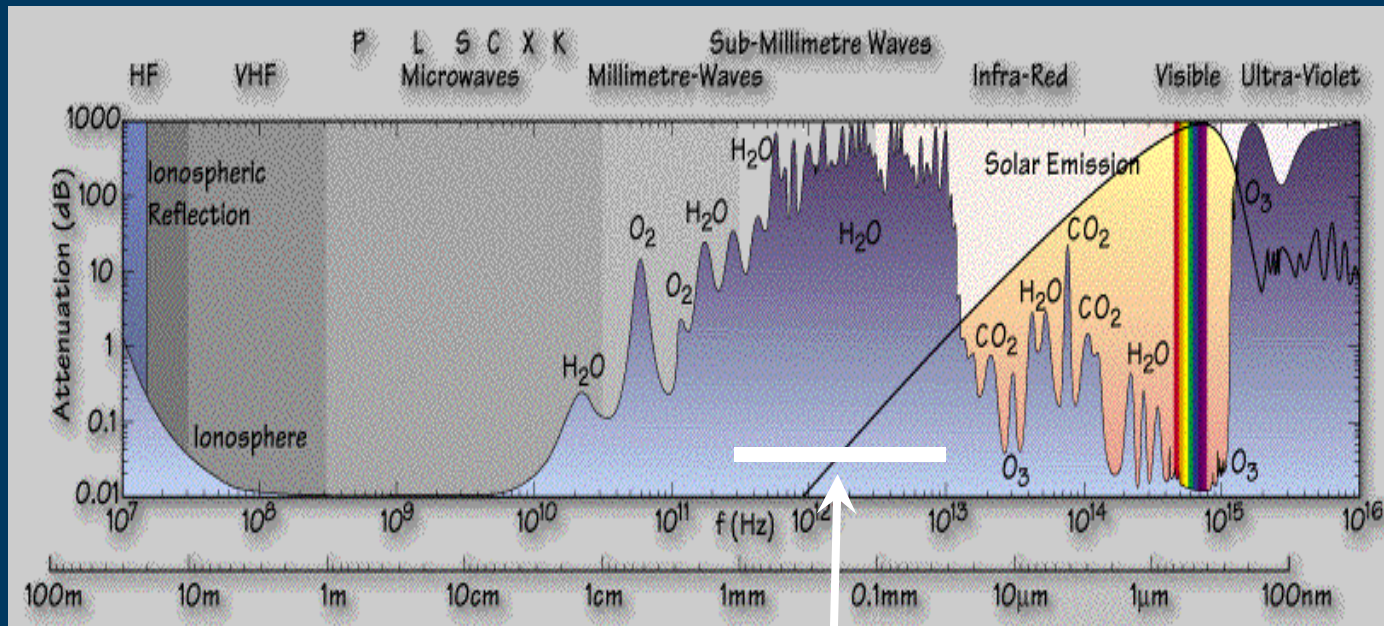
Research

High Frequency & Quantum Electronics

Prof Dr Peter Haring Bolívar



The THz Frequency Range



$\nu = 300 \text{ GHz} \dots 10 \text{ THz}$

$\lambda = 1 \text{ mm} \dots 30 \mu\text{m}$

$k = 10 \text{ cm}^{-1} \dots 300 \text{ cm}^{-1}$

THz is at the transition
from electronics to optics

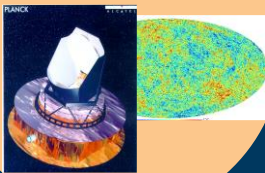
$$\nabla \times \vec{H} = \vec{j} + \frac{\partial \vec{D}}{\partial t}$$

The equation shows the curl of the magnetic field vector $\vec{H}$ equal to the sum of the current density vector $\vec{j}$ and the time derivative of the electric displacement vector $\vec{D}$. An orange arrow points to the $\vec{j}$ term, and a green arrow points to the $\frac{\partial \vec{D}}{\partial t}$ term.

THz Imaging & Sensing Areas

Environment

e.g. astronomy, crops, gases, contamination, ...



Ultrafast sensors

e.g. DUT analysis, circuit test, device optimization, ...



THz communications

e.g. WAN, WPAN, Chip-to-chip, ...

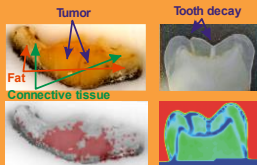


6G

„Emerging“

Medical

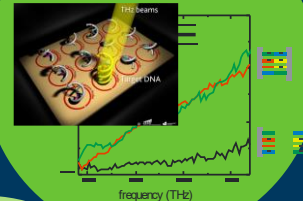
e.g. tumor or caries recognition



THz imaging & sensing

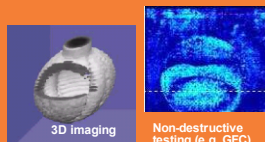
Biotech

e.g. genetic & proteomic sensing, biochips



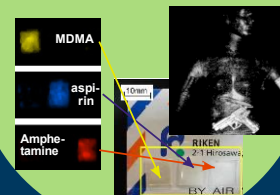
Industrial

e.g. package inspection, process control



Security

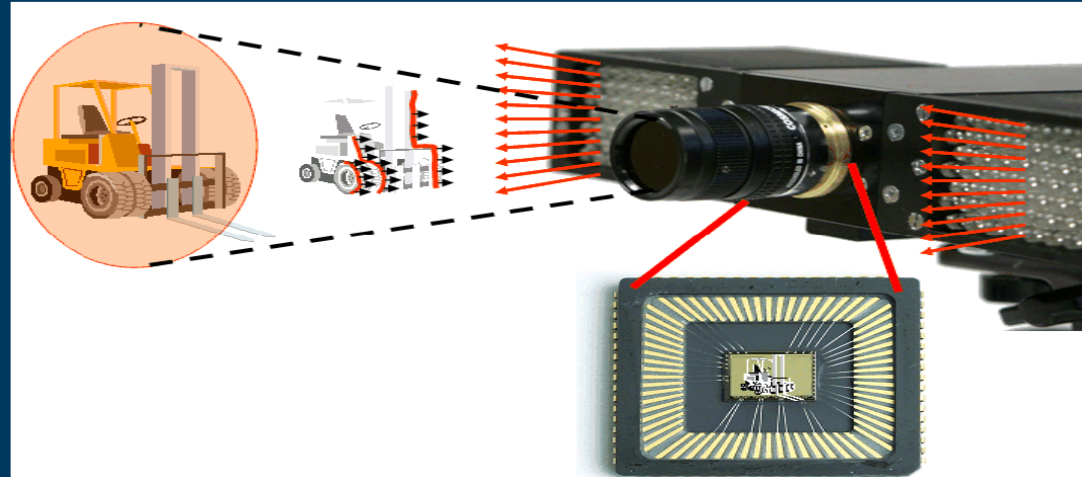
e.g. drug & explosives detection



P. de Maagt, P. Haring Bolivar and C. Mann, Encyclopedia of RF and Microwave Engineering, pp. 5175-5194 (John Wiley & Sons, Inc., 2005) ISBN 0-471-27053-9.

3D Cameras

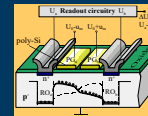
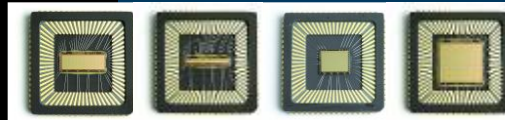
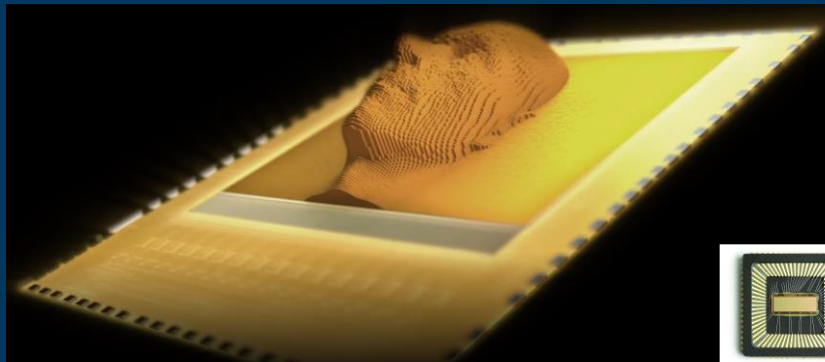
- The AI-infused world is characterised by intelligent technical systems that need to interact reliably with people and each other.
- 3D vision (seeing and recognising) is a crucial prerequisite.



Reliable high resolution 3D-measurements with active optical sensors

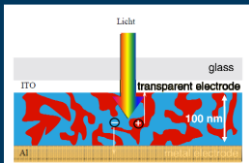
3D Camera Spin-offs

- *Real-3D* with Si-integrated Sensors with active illumination (ToF) (Prof. Schwarte)



Durchbruch durch größere Verbundprojekte, wie z.B. BMBF Projekt LYNKEUS (>1000 Personenmonate) und Industriekonsortia. Eintritt in Massenmärkte gelungen (zB Lenovo, Leica, ...)

- Further Spin-off from BASF research activity (Dr. Thiel, Prof. Haring Bolívar)



Organische Zelle; Fundamentalbeobachtung und Effekterklärung im Rahmen Industrieprojekt mit BASF/ERT Optik



> 100 Staff



Nominated "Zukunftspreis 2002"



> 50 Staff

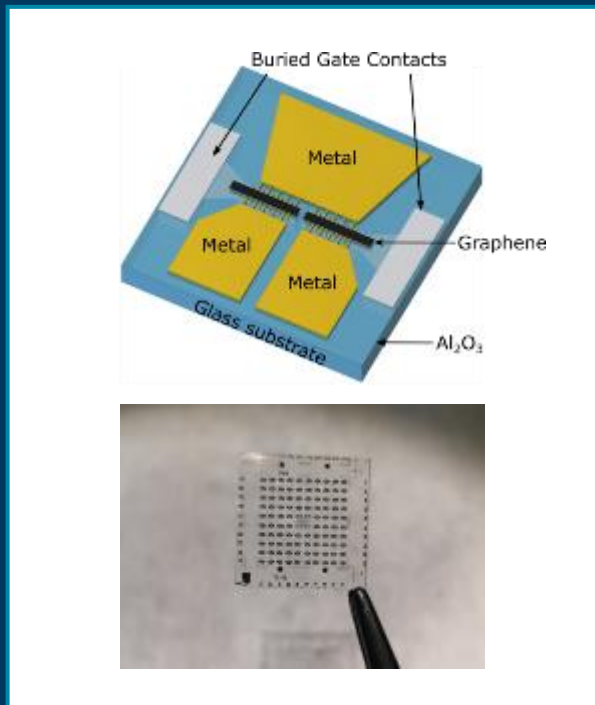


Nominated "AMA Innovation Award 2019"

3D Camera Development

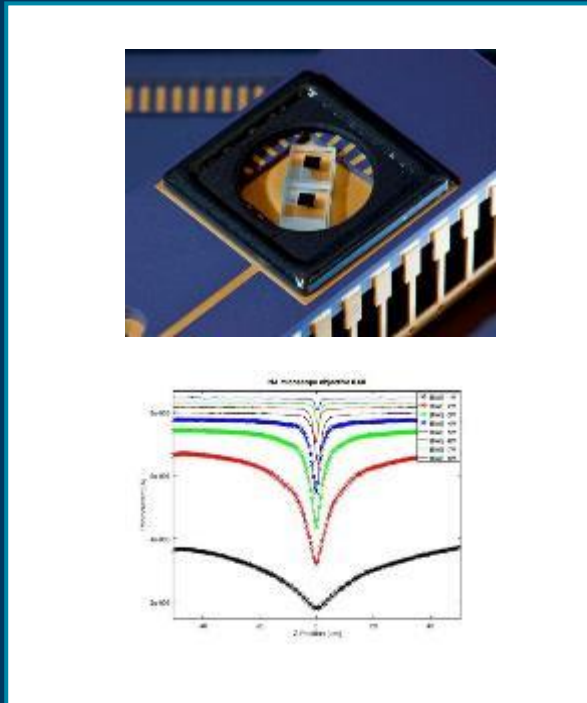
Heterogeneous Integration

- 2D Materials (Graphene) on Si



Passive Direct 3D

- Nonlinear. a-Si photodiodes



Cooperation Haring Bolívar, Kolb, Lemme, PMDTec, Charbón, et al.

Computer Graphics

Prof Dr Andreas Kolb



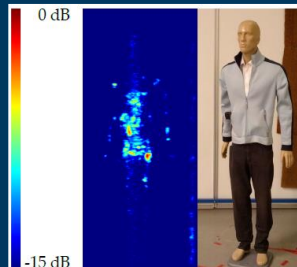
Sensor Simulation

- Various modalities, e.g., color, depth, THz, and multispectral
- Physically based sensor & scene models

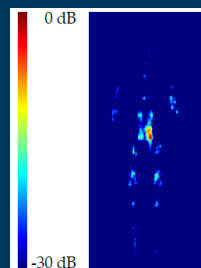
Real Depth Data



Real THz Data



Sim. THz Data

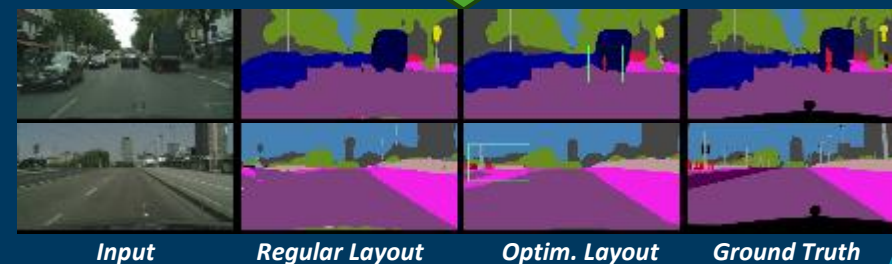
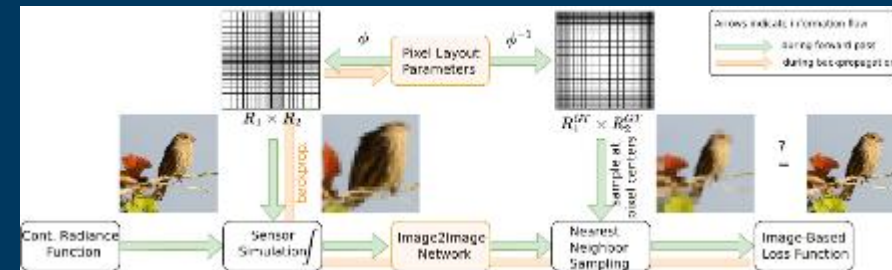


Sim. Depth Data



Sensor Optimization

- Variation of sensor parameters, such as pixel layout or color filter
- Joint learning of task and sensor parameters



Model-driven Sensor Data Fusion

- Interactive for high data rates
- Sample tasks: real-time scene or image reconstruction



Low Feature Scene



3D reconstruction

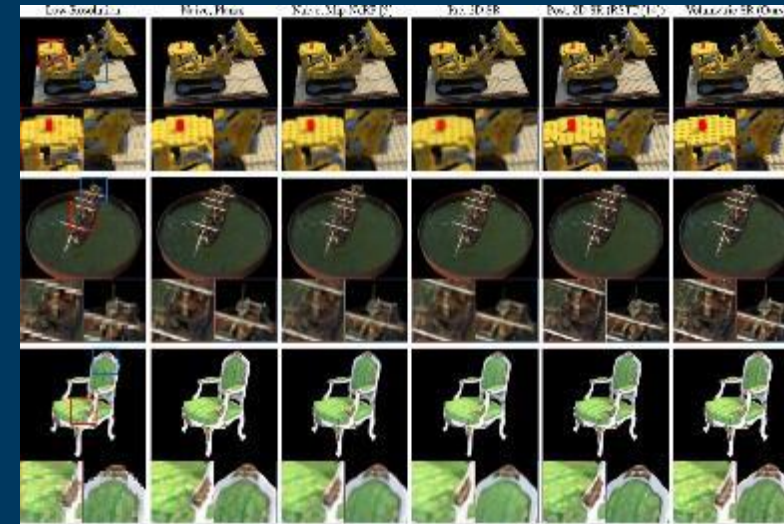


Reference offline
optimization

Our online2D
reconstruction

Data-driven Sensor Data Fusion

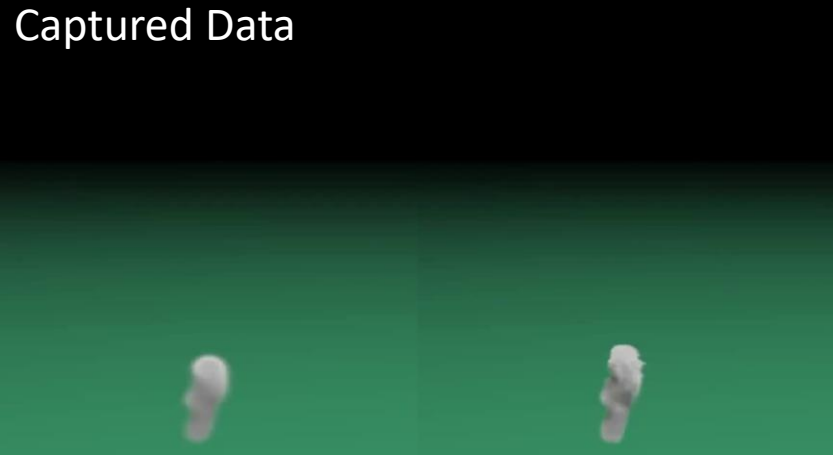
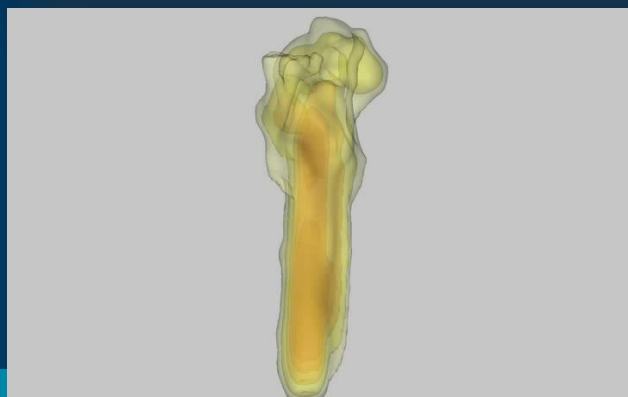
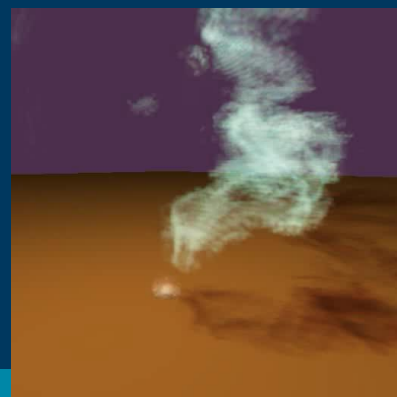
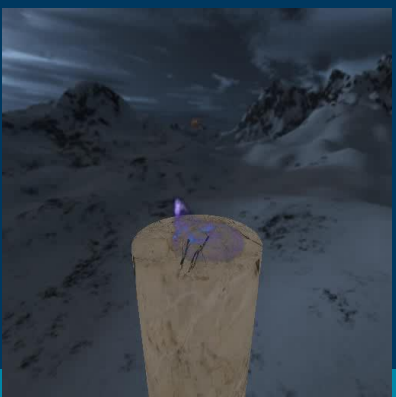
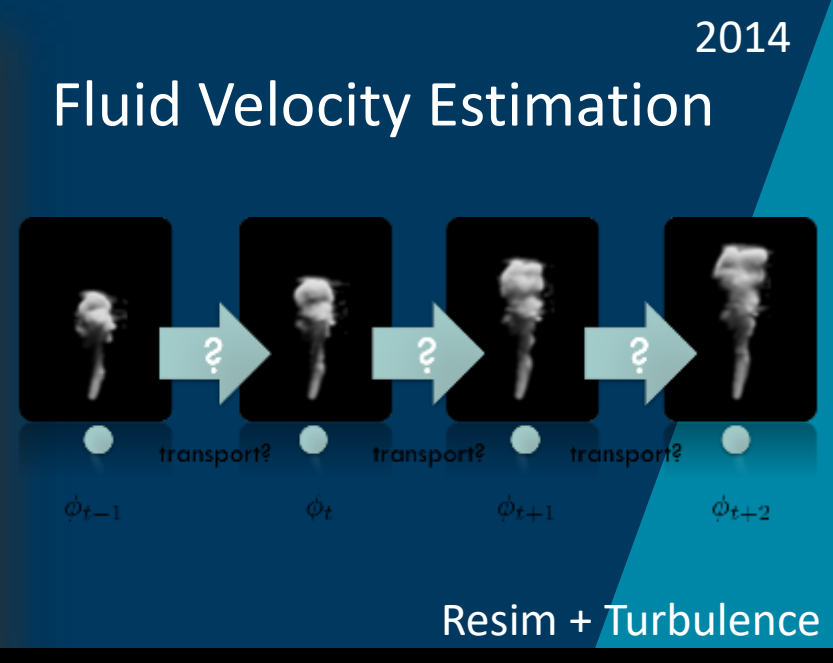
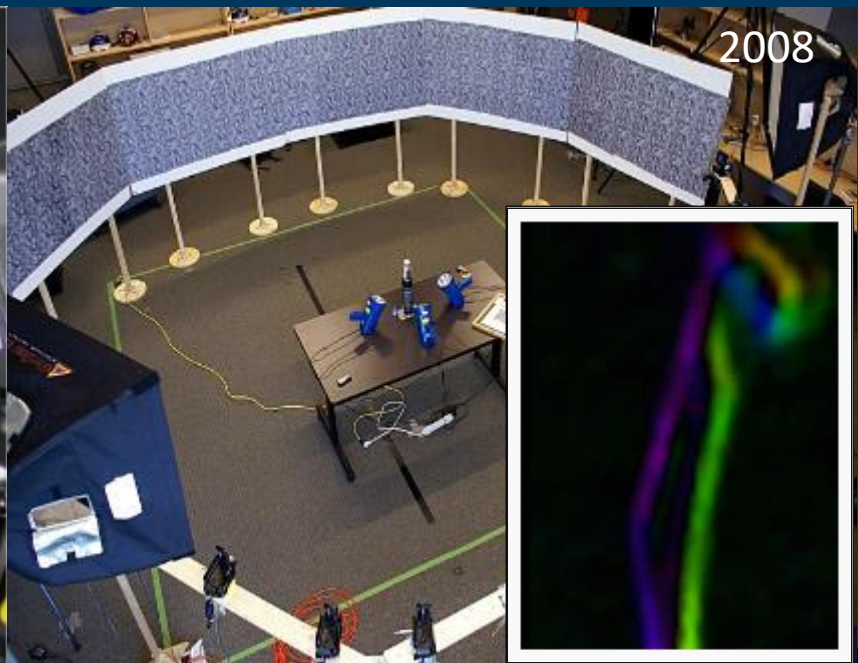
- Neural scene representation (NeRF and Gaussian Splatting)
- Sample task: Super-resolution



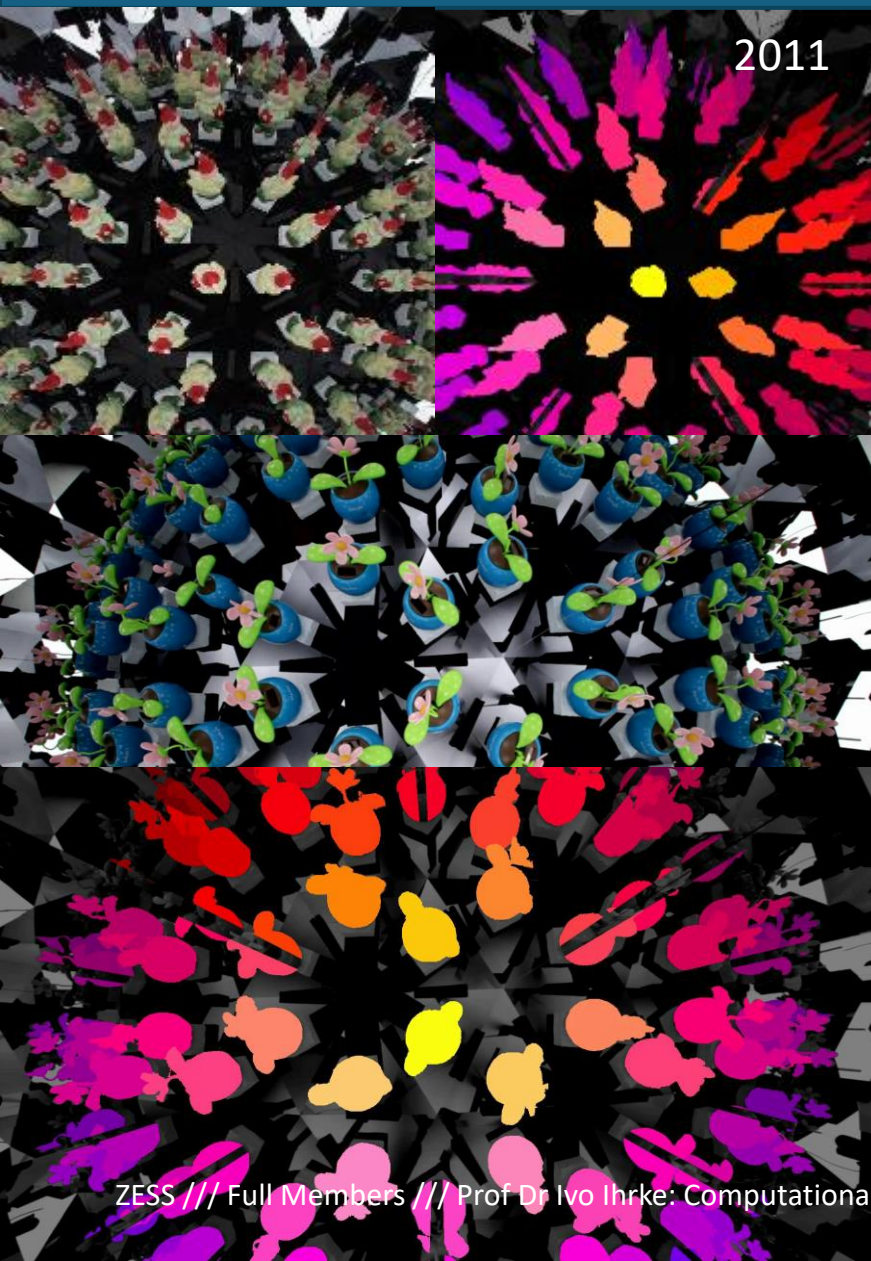
Computational Sensorics & Commu- nications Engineering

Prof Dr Ivo Ihrke

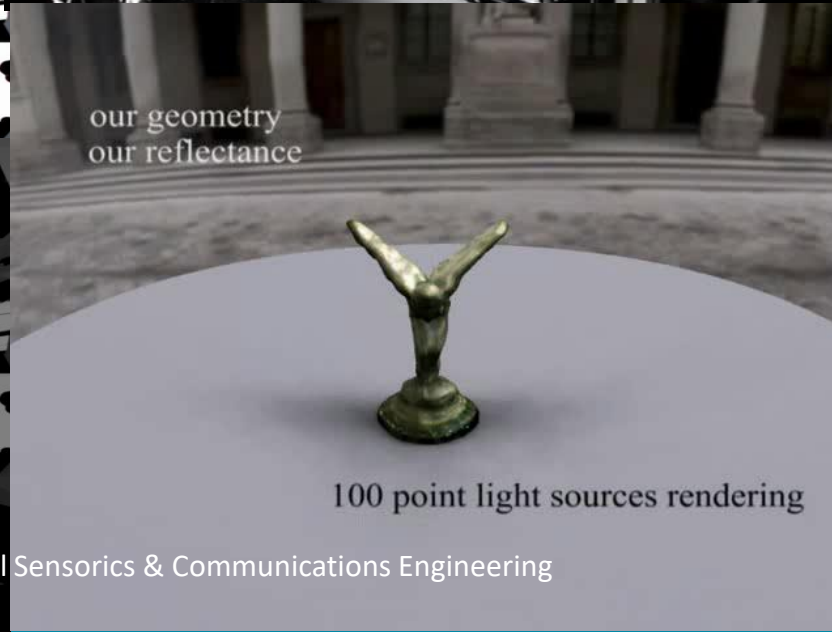
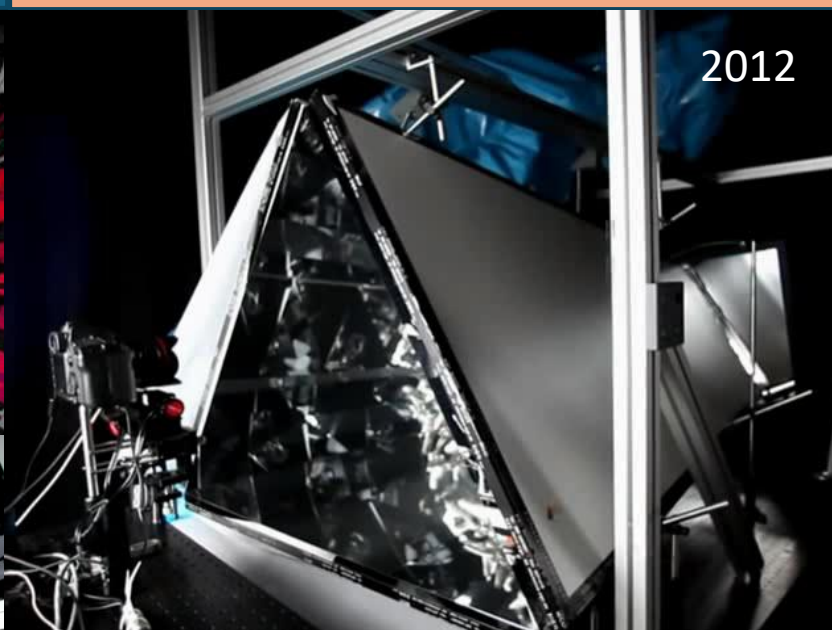




Kaleidoscopic Imaging: Multiplexing Many Views



Bidirectional Kaleidoscope: Simultaneous Geometry and Reflectance



K|Lens A New Light Field Imaging Architecture



APPLICATION: VIRTUAL F/0.7 REFOCUSING



Image Processing

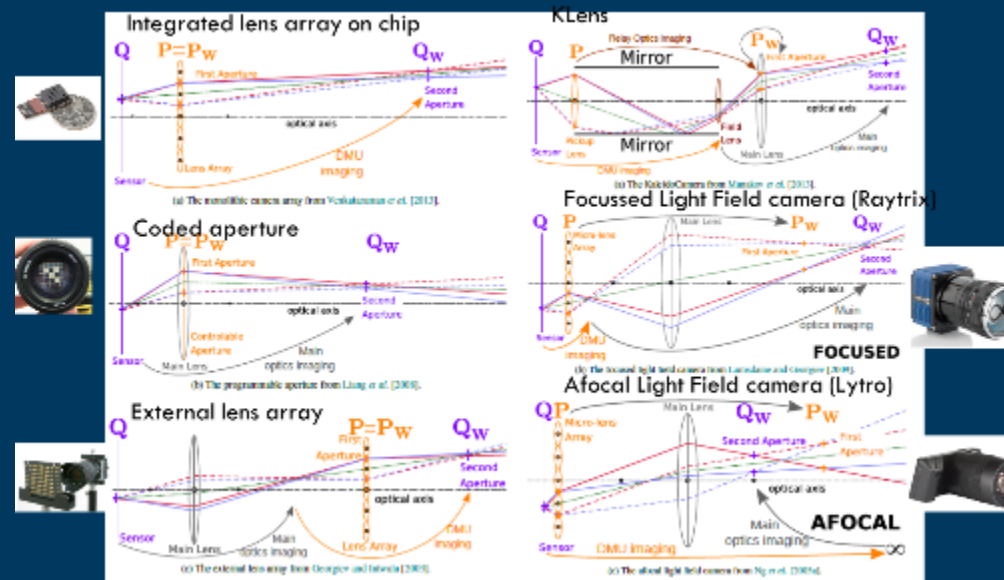
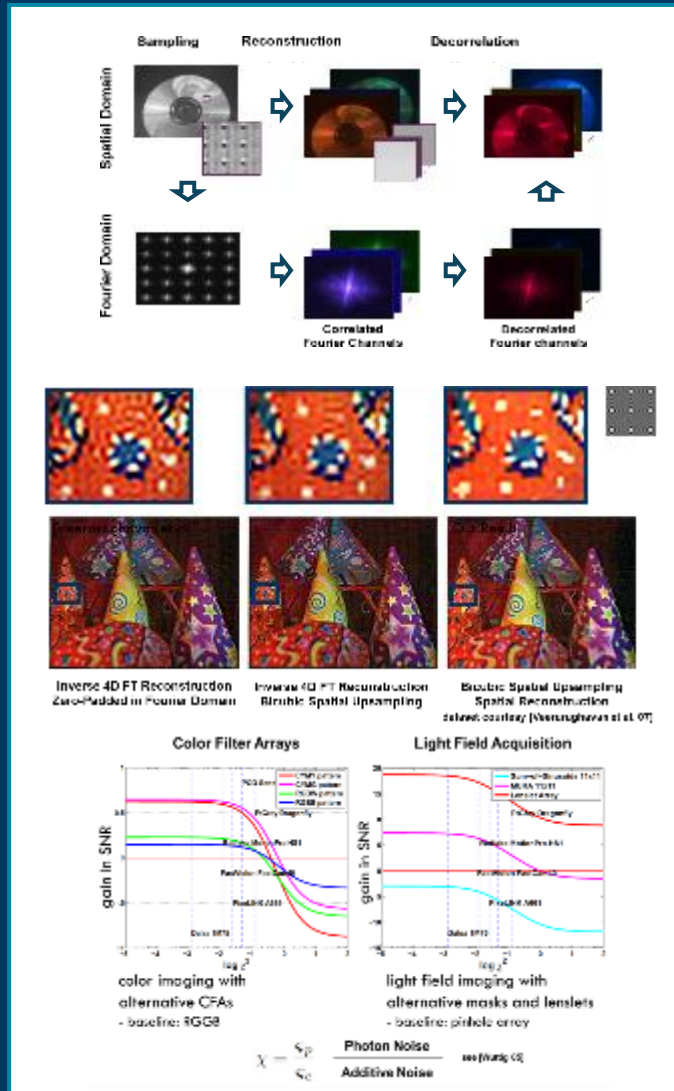
Plenoptic Sampling & Reconstruction

Optical Models

Unifying First-Order Light-Field Theory

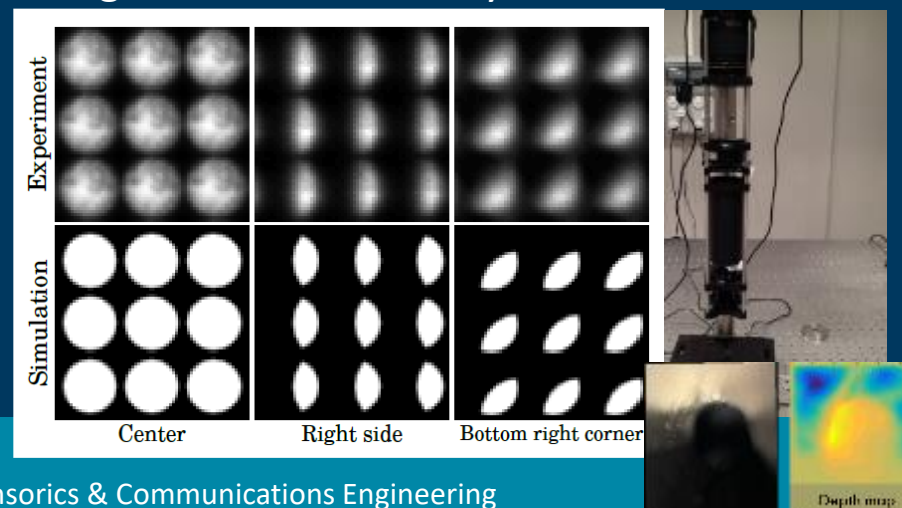
Optical Models

Aberrations



Optical Models

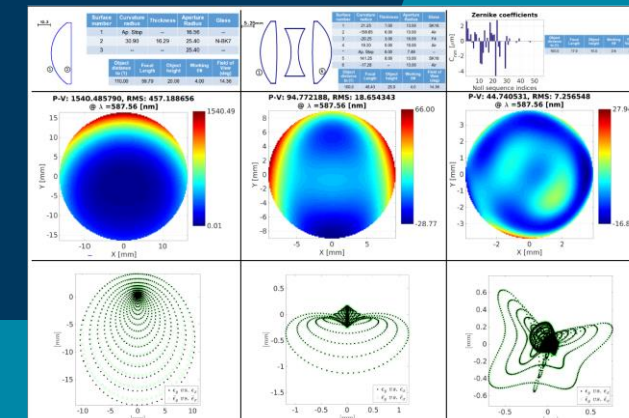
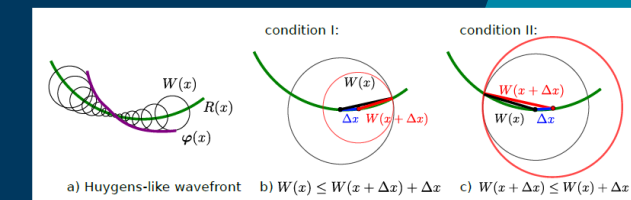
Light Field Radiometry



$$\frac{\partial W}{\partial x} \approx -\frac{\epsilon_x}{r}, \text{ and}$$

$$\frac{\partial W}{\partial y} \approx -\frac{\epsilon_y}{r},$$

Long-standing problem:
This is just an approximation
New: Exact Analytical Solution



Snapshot Plenoptic Imaging

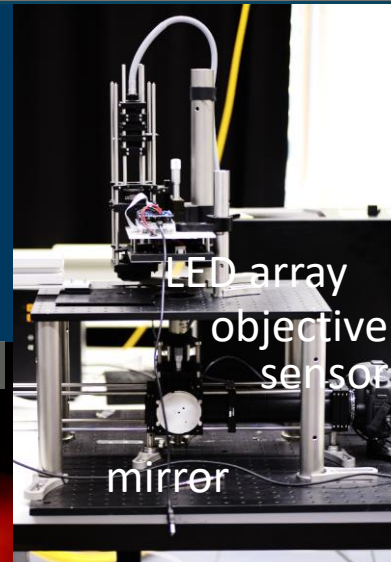
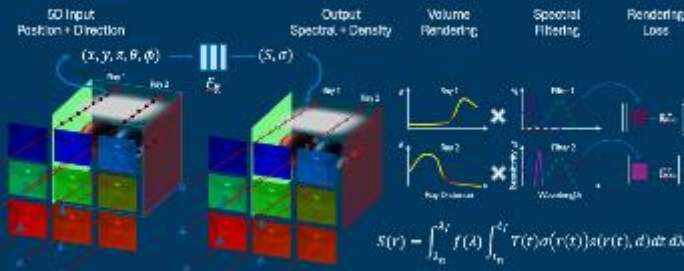


Depth Estimation



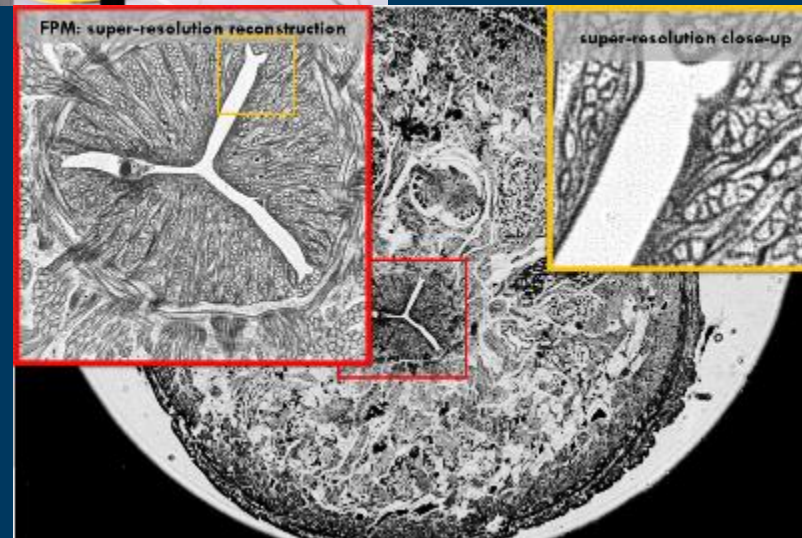
Spectral Light Field Imaging

□ Spectral Neural Radiance Field Scene Representation



Fourier Ptychographic Microscopy

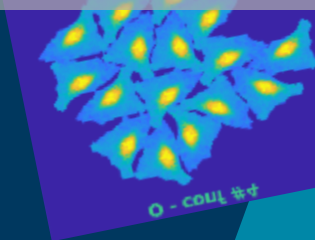
System Characterization and Calibration
Optical Analysis and Algorithm Development



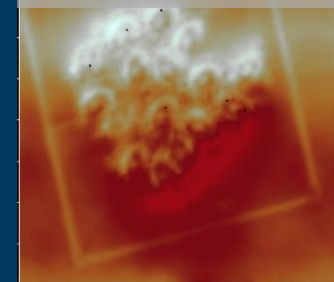
3D printed ground truth



ground truth phase map



captured phase map



acousto-fluidic device



sustained sample rotation



Mechanics & Structural Health Monitoring

Prof Dr Peter Kraemer

ZESS Co-Speaker & Member of the Board



Condition and Structural Health Monitoring



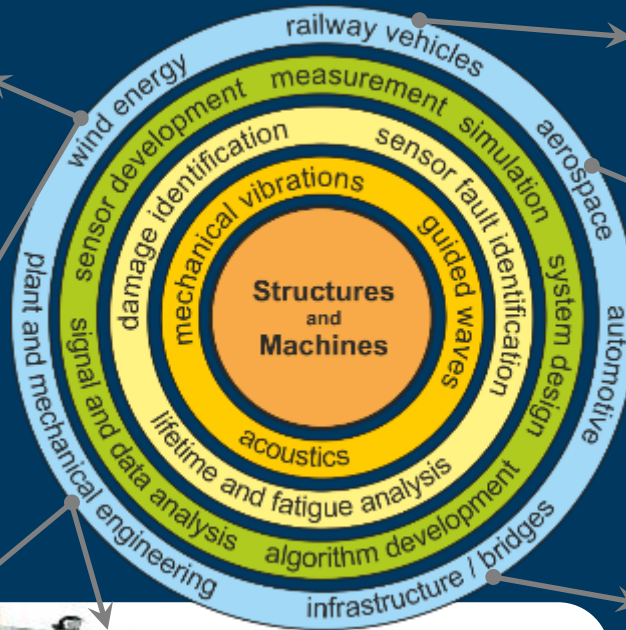
SHM of
Rotor blades

Fleet
Monitoring

SHM of
• Grout
• Foundation
• Tower

Control engineering for
welding of tower segments

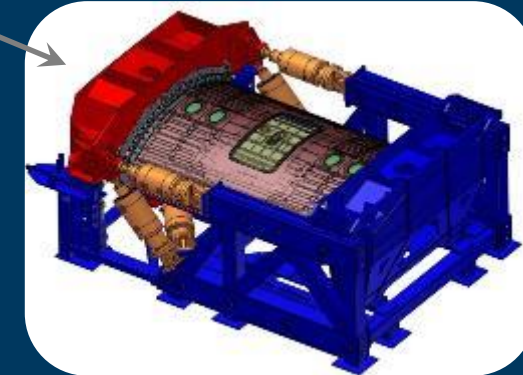
Condition Monitoring
(CM)
of drive trains



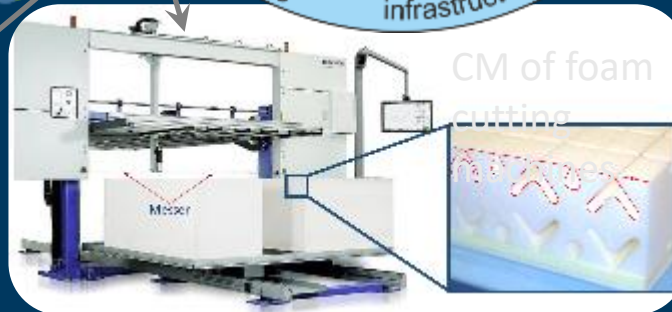
Sensors,
automatic fault
detection for rail
vehicles



CM of
aerospace
structures



CM of foam
cutting



SHM of rail bridge
components



MSHM access to „large test rigs“

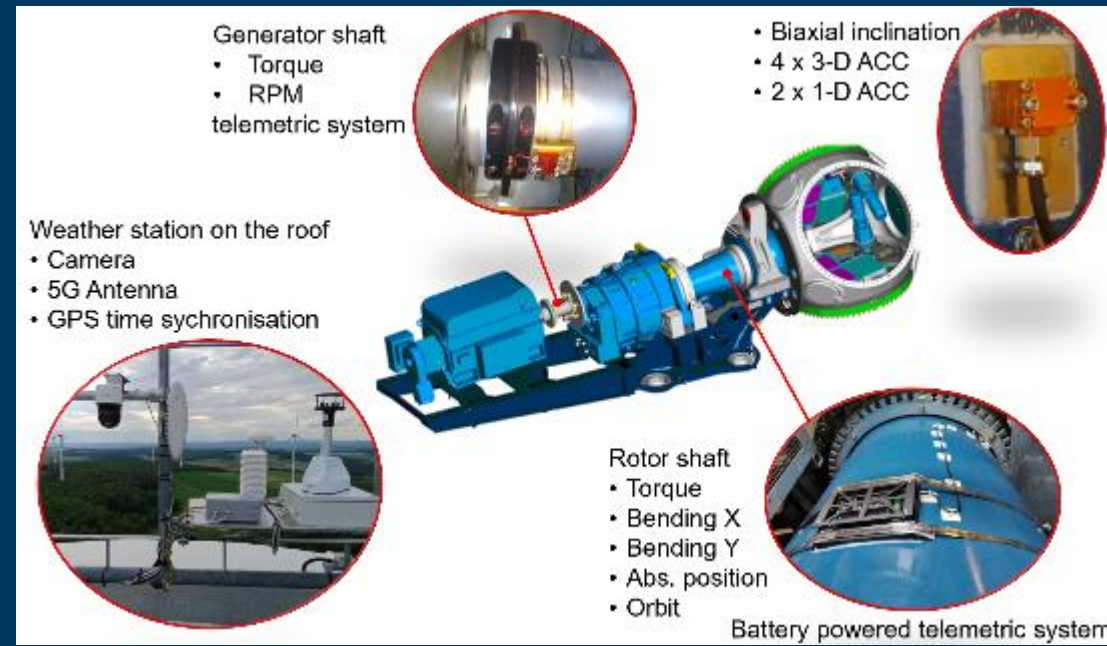
Contract between BEA eG and
MSHM of University of Siegen



Research on BEA-WEP is allowed for
the lifetime of the plant

Tower, blades and drive train are installed with > 100 sensors

Example of drive
train installation



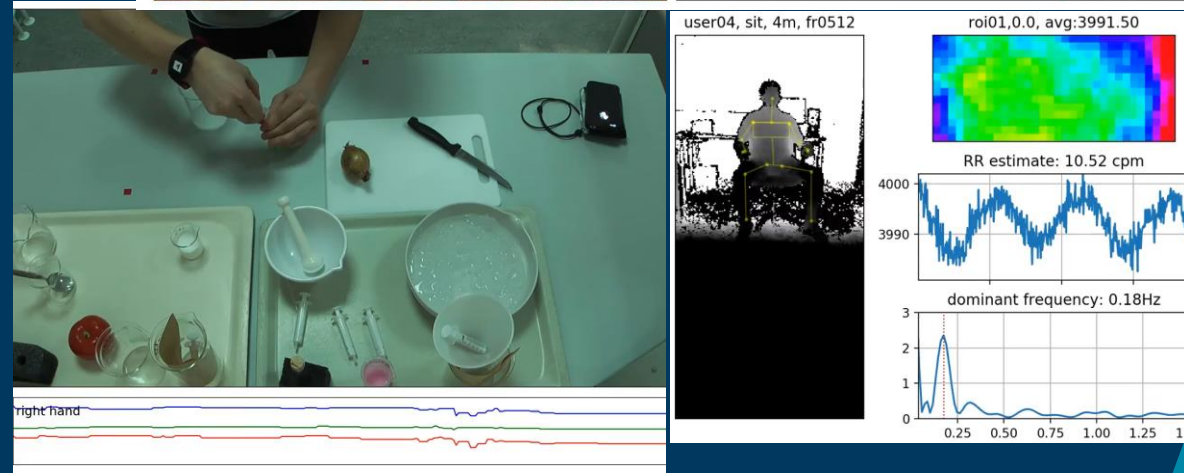
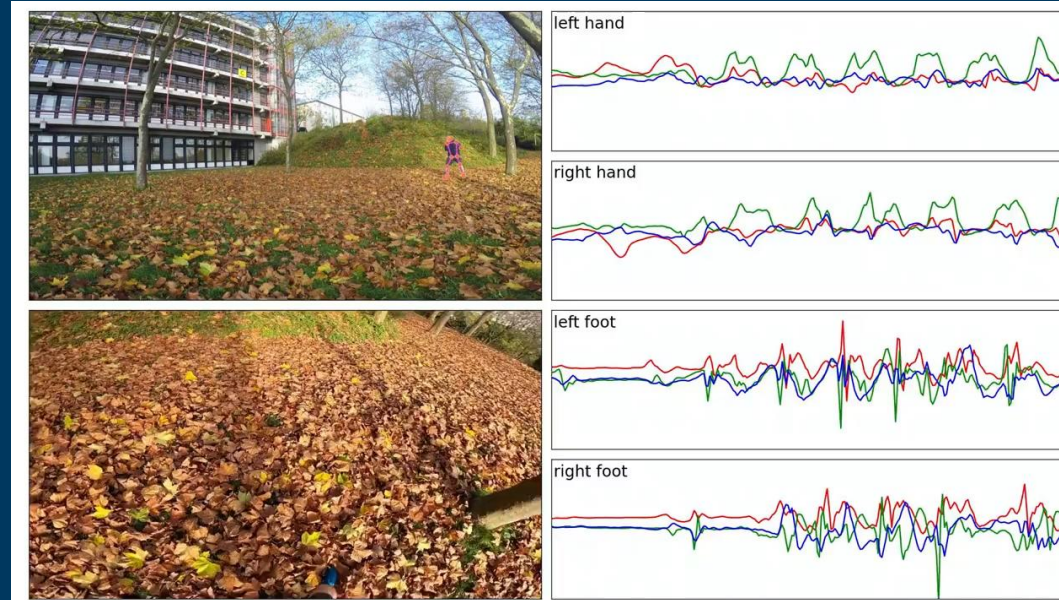
Ubiquitous Computing

Prof Dr Kristof Van Laerhoven

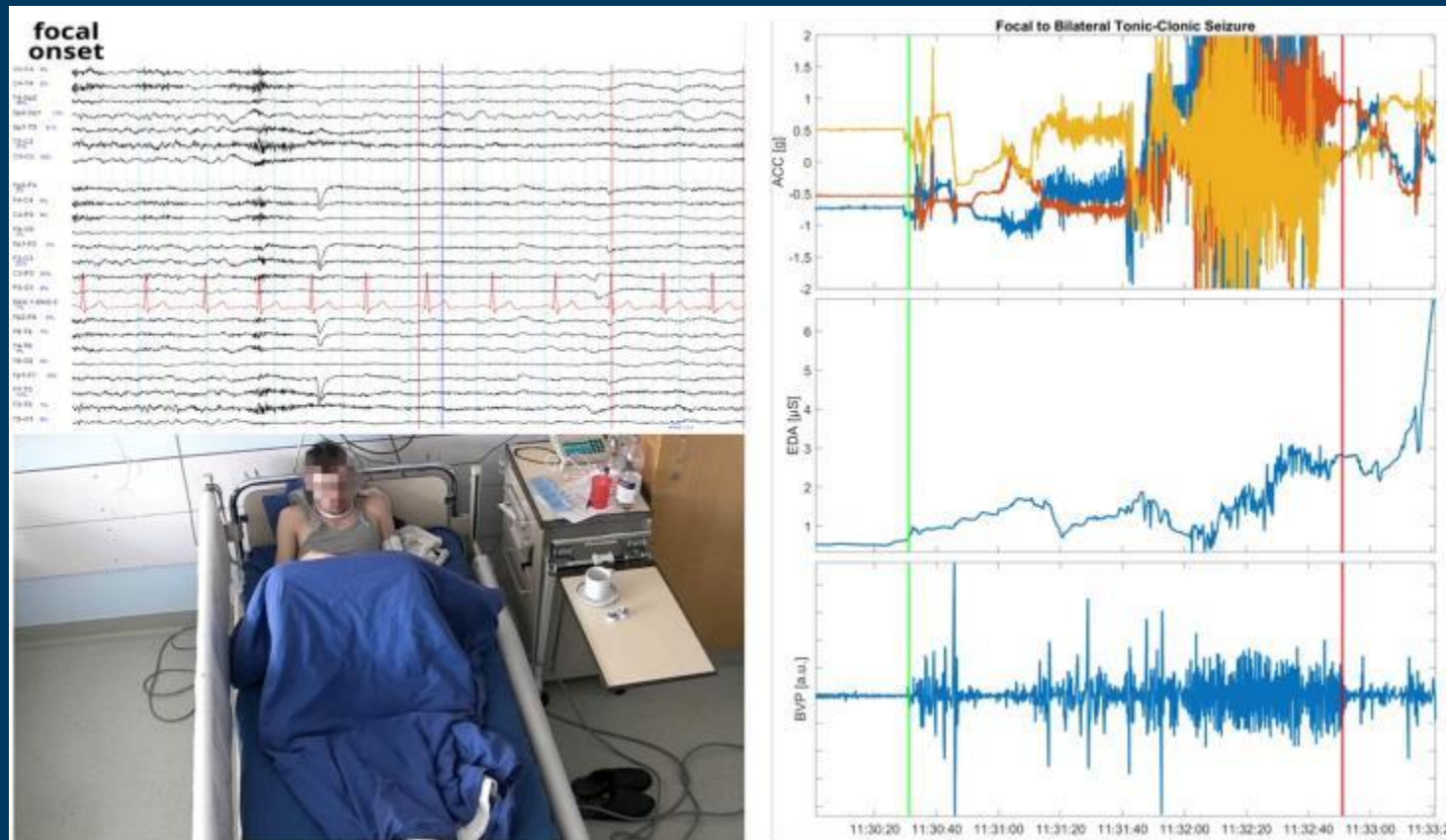
ZESS Speaker & Member of the Board



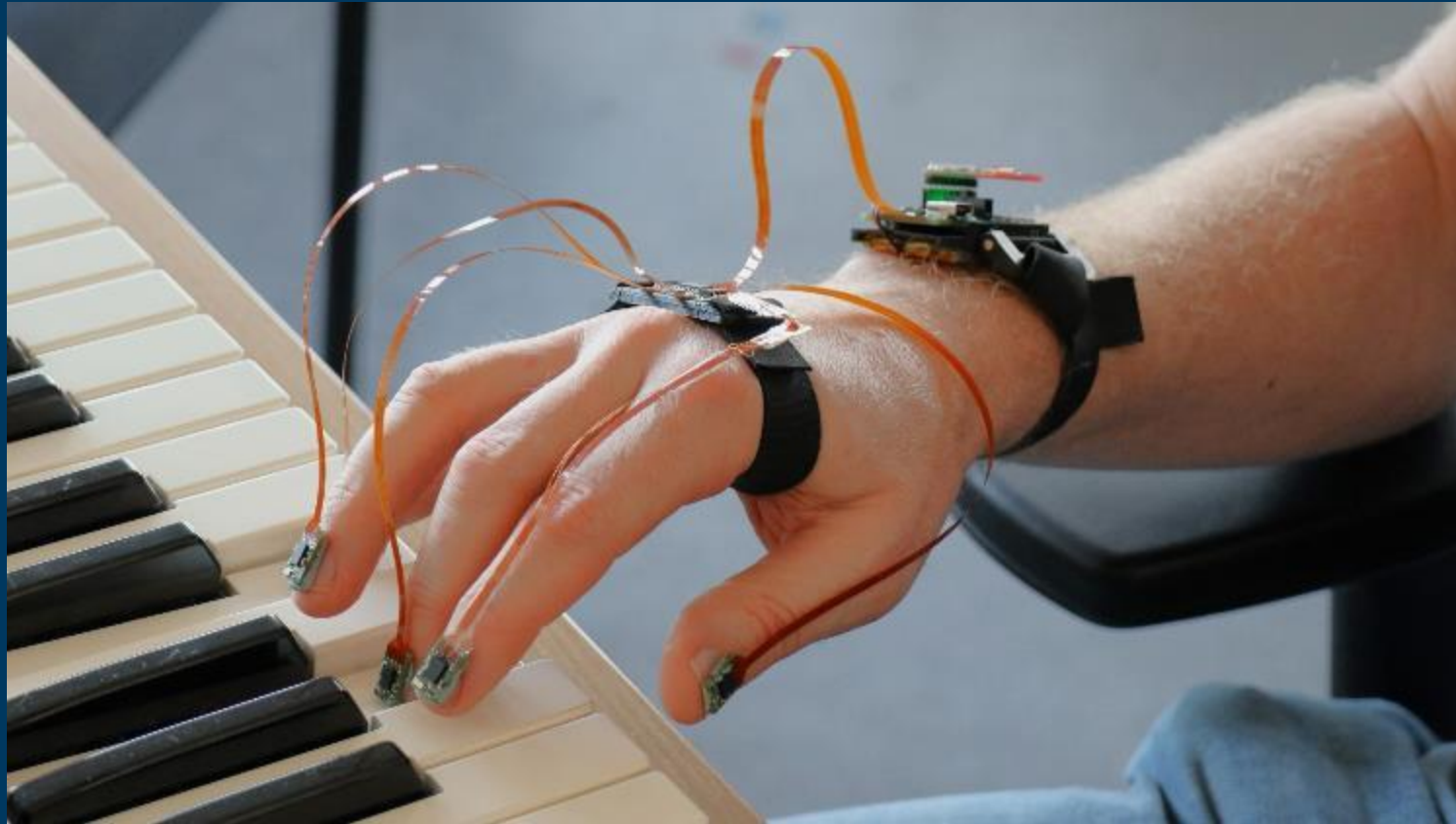
Ubiquitous Computing



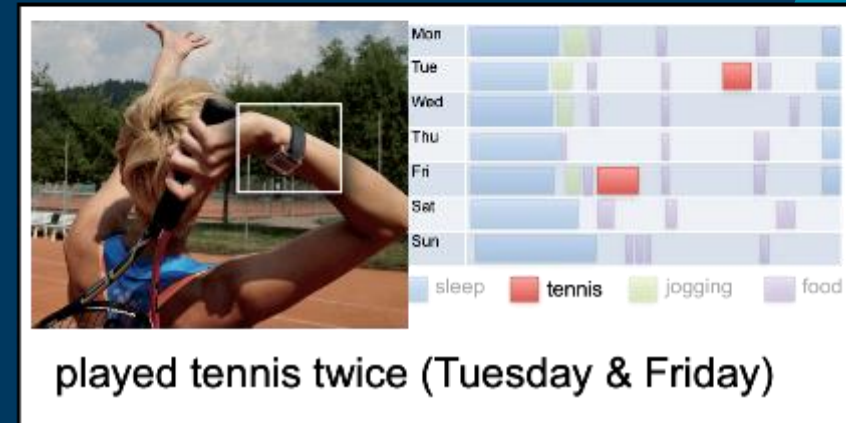
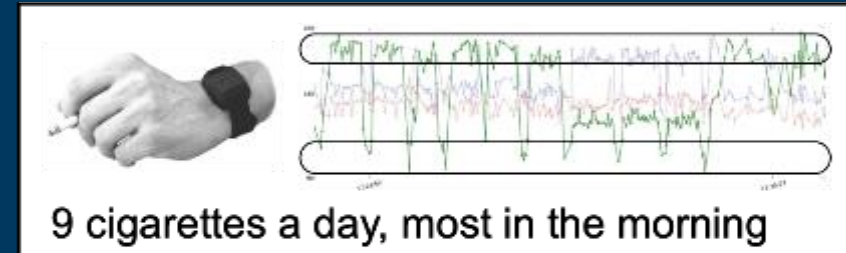
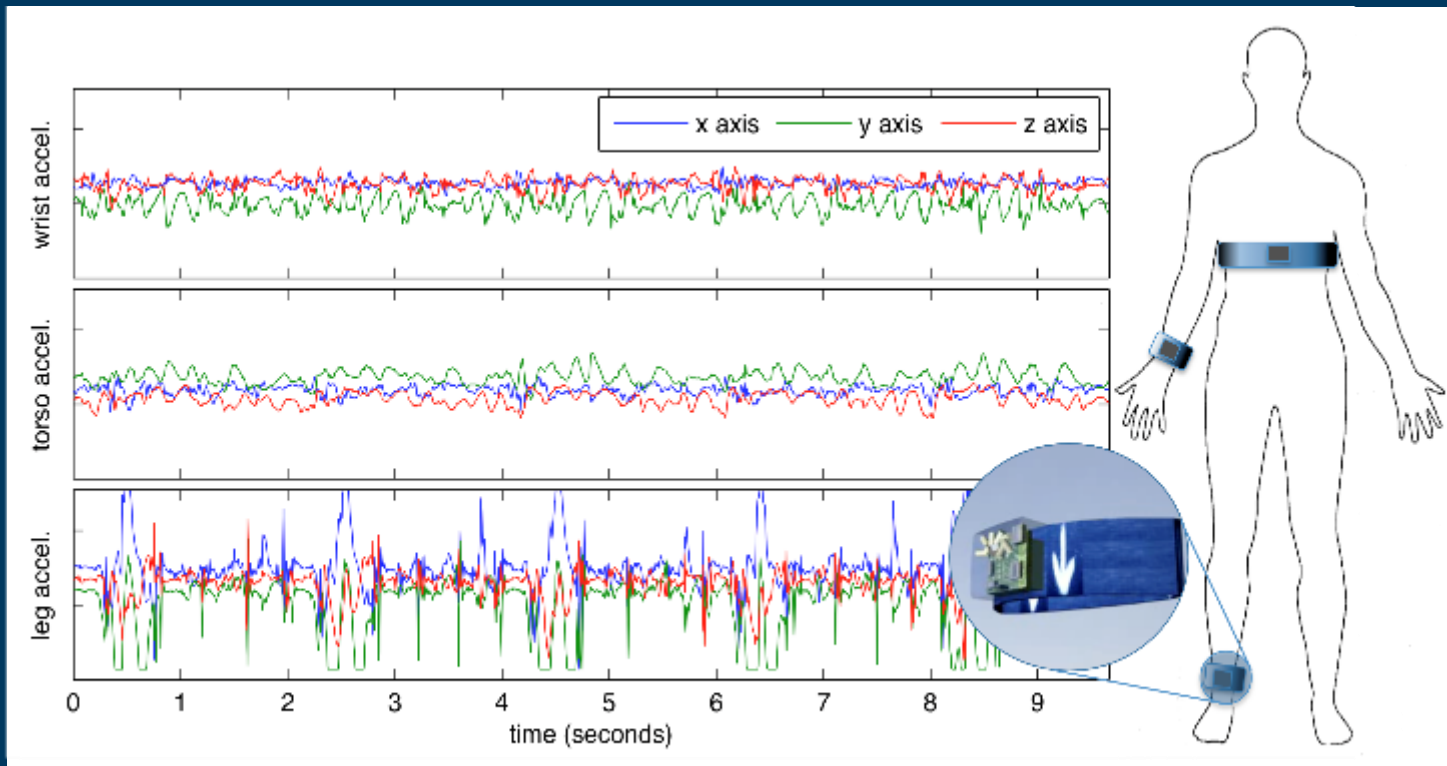
Detecting Epileptic Seizures with Wearable Sensors



Wearable Sensors for Capturing Hand Articulation



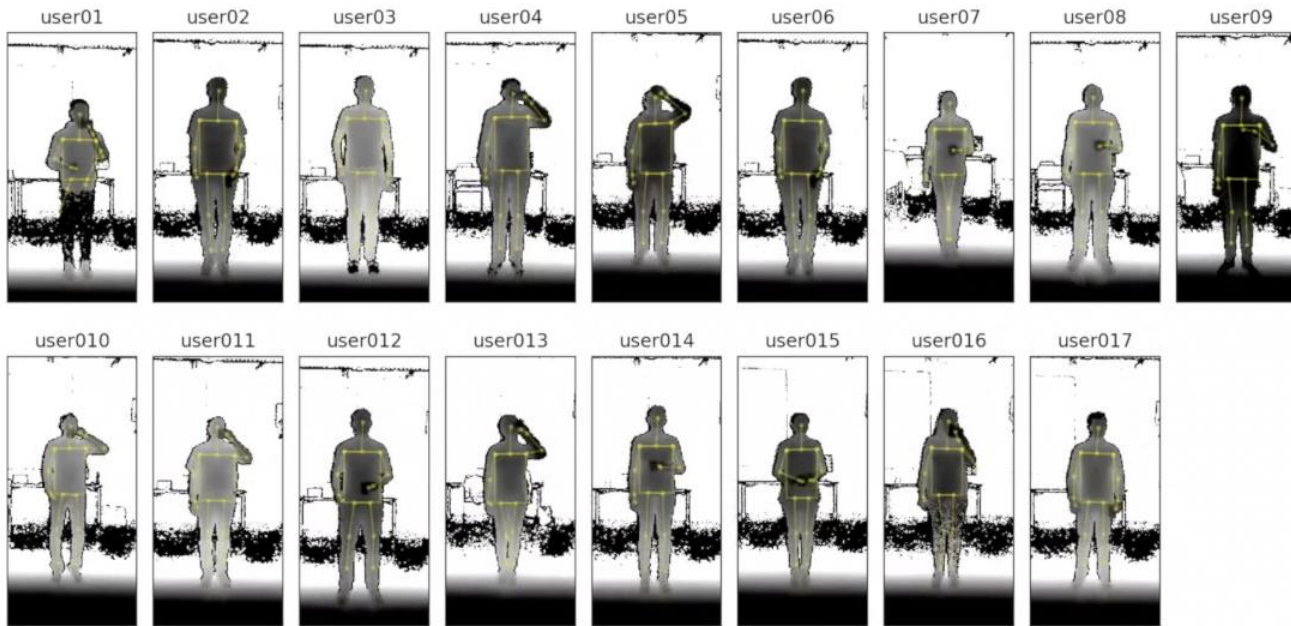
Activity Recognition



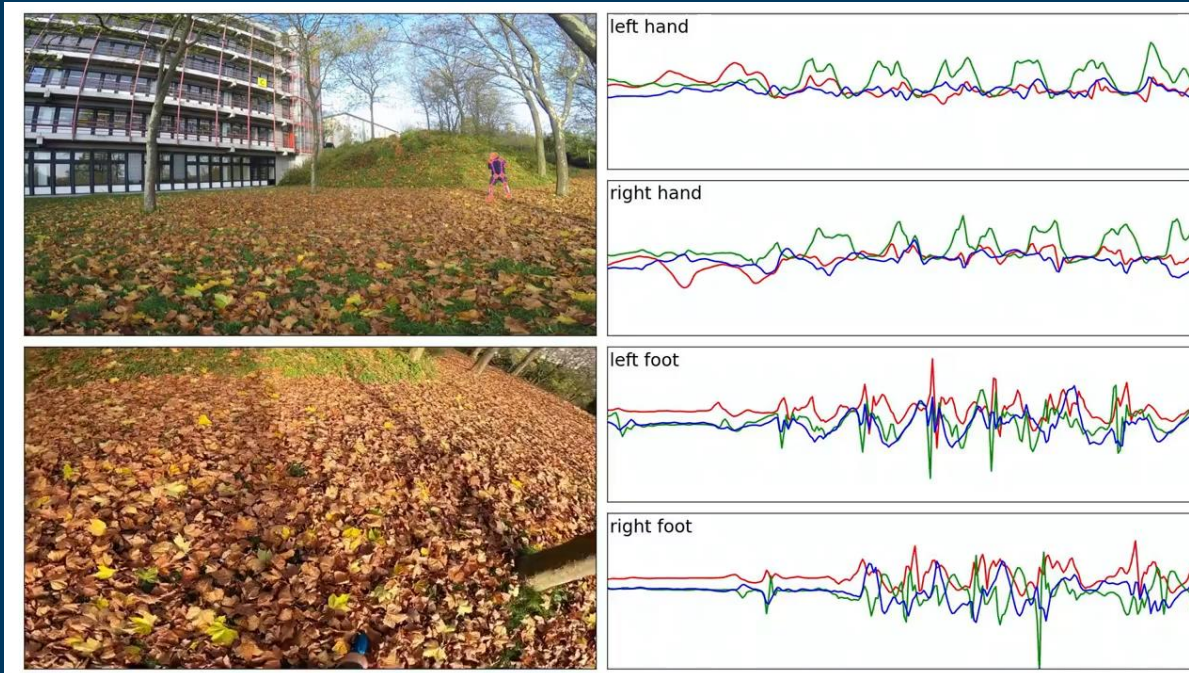
Respiration Monitoring with Depth Cameras

The dataset:

17 participants (age: 22-57, 5 female)



WEAR: An Outdoor Sports Dataset



> 15 hours
615 action segments
10 outdoor locations
4 seasons



18 participants
♂ 10 ♀ 8
28 ± 5 years old



min. 2 sessions
18 workout activities
5 running, 5 stretching &
8 strength



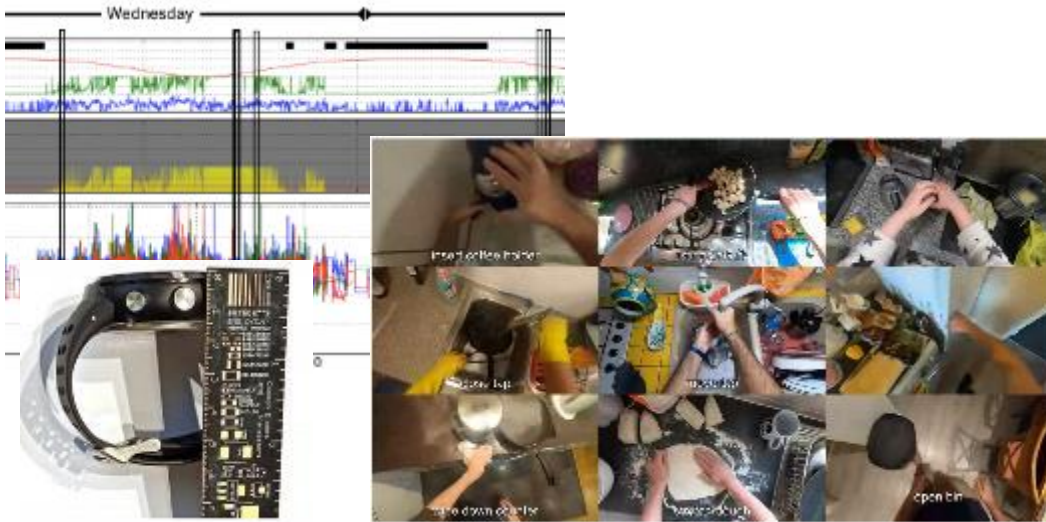
WEAR: An Outdoor Sports Dataset for Wearable and Egocentric Activity Recognition,
Marius Bock, Hilde Kuehne, Kristof Van Laerhoven, and Michael Moeller. ACM IMWUT
2024 <https://mariusbock.github.io/wear/>

Computer Vision

Prof Dr Michael Möller



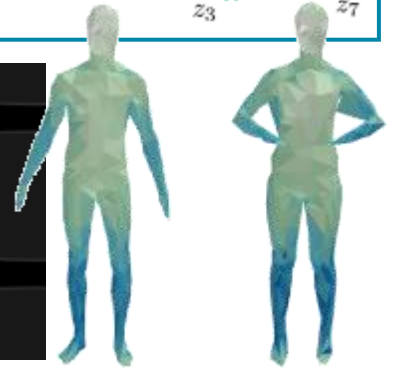
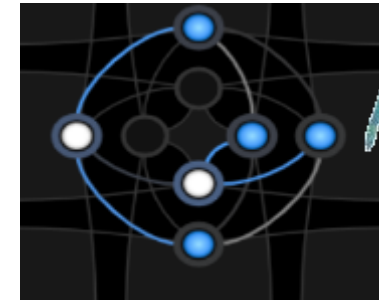
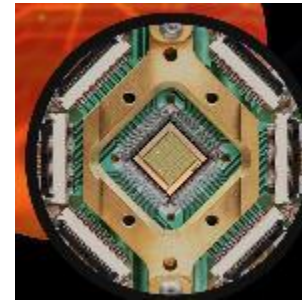
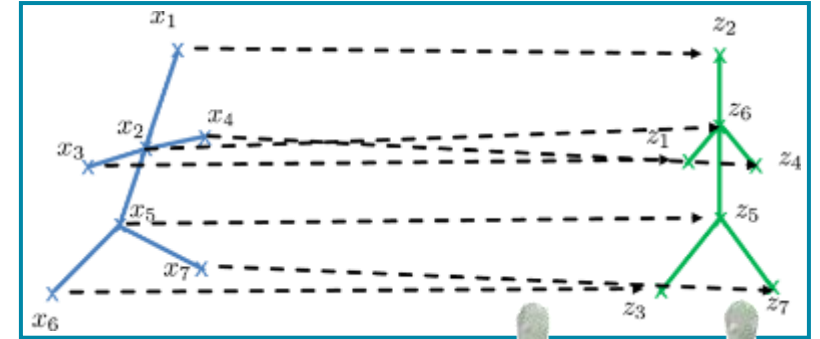
Computer Vision I



Human activity recognition with visual and body-worn sensor data.

<https://shop.espruino.com/banglejs>

<https://epic-kitchens.github.io/2023>

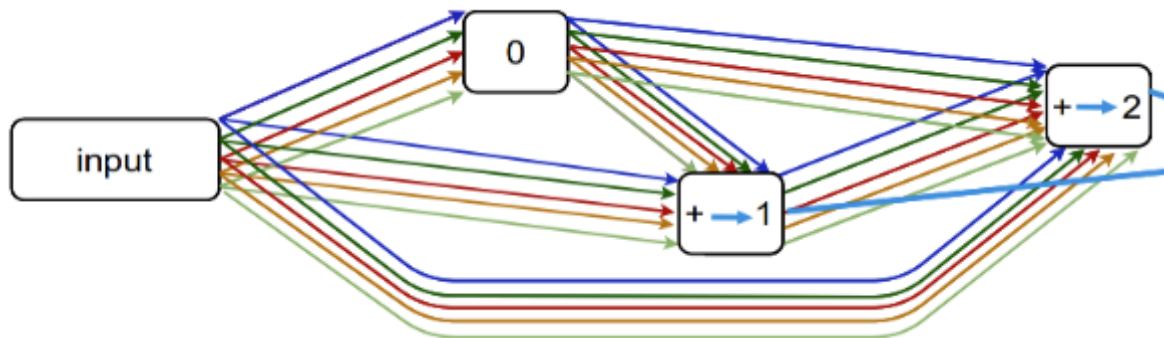


Matching problems and quantum computer Vision

Images taken from D-Wave

Computer Vision II

(Robust) Neural Architecture Search

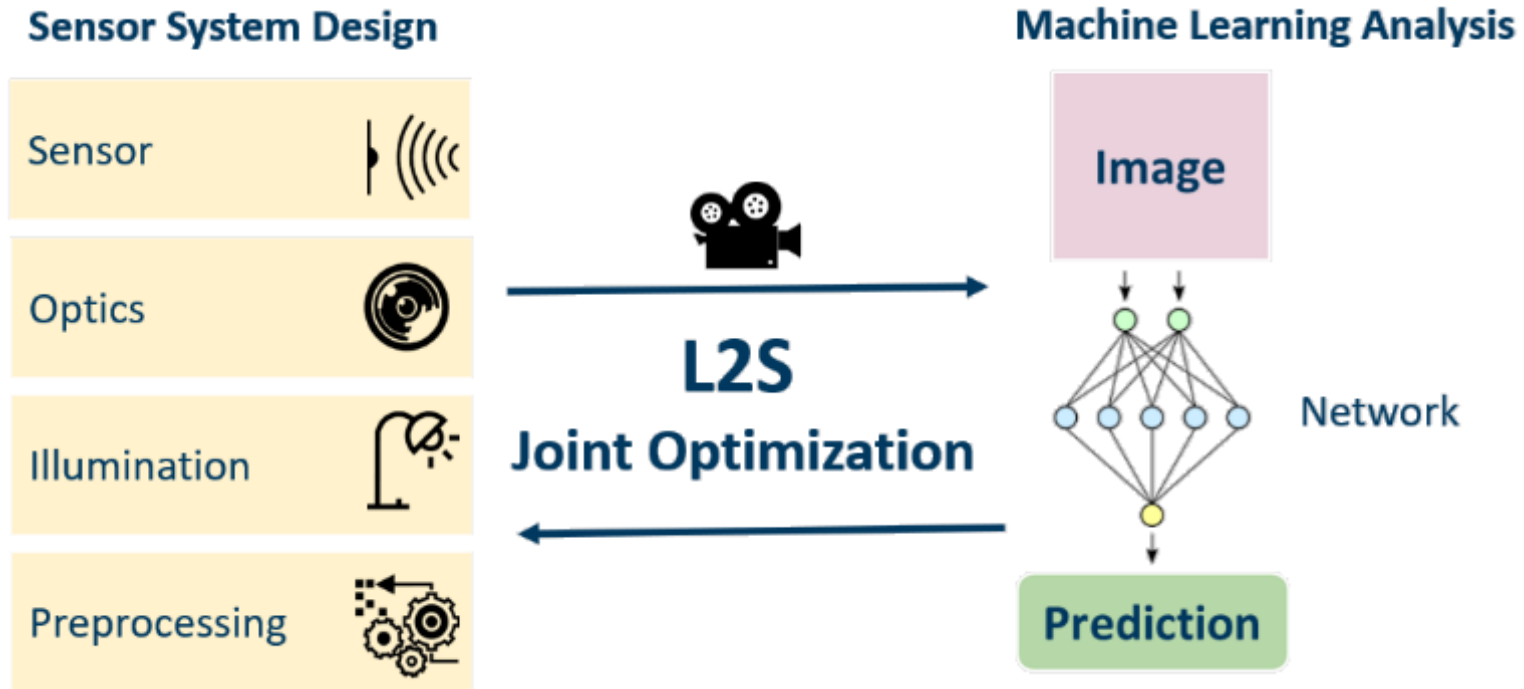


From: *Differentiable Architecture Search*, AutoML Conference 2023 Workshops

Industry:
Sensors & processing
for atrial fibrillations

Inverse Problems in Imaging I

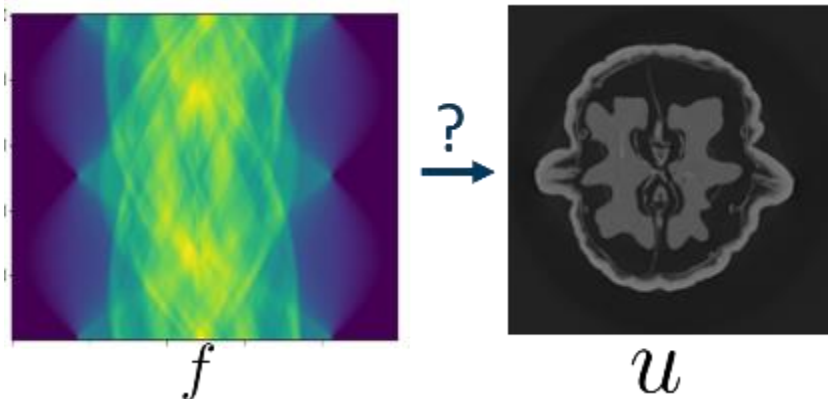
Machine learning for joint hardware & software optimization



Inverse Problems in Imaging II

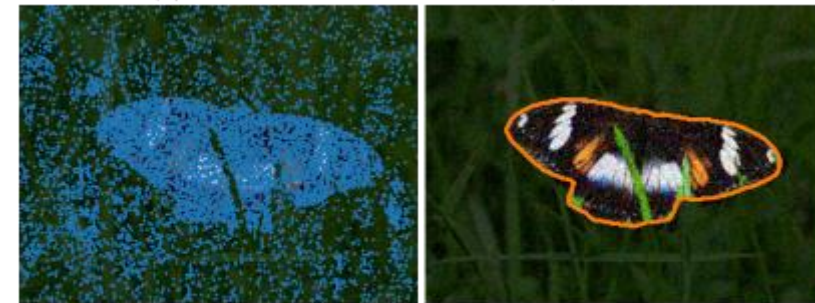
Understanding Machine Learning, e.g.

- **Inverse Problems** with provable guarantees
- **Implicit Representations** to constrain neural networks
- **Little training data**; language models



(a) Naïve

(b) Convex



(e) Naïve

(f) Mirror Symmetric

Automatic Control – Mechatronics

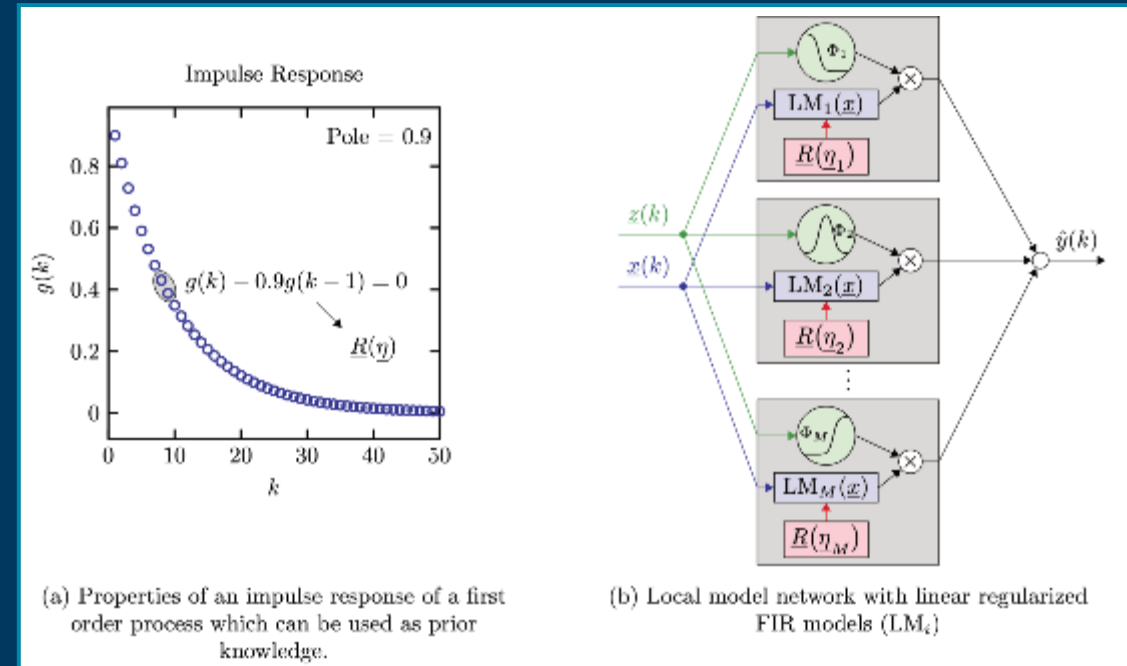
Prof Dr Oliver Nelles



Nonlinear System Identification

Nonlinear Regularized Finite Impulse Response (FIR) Models

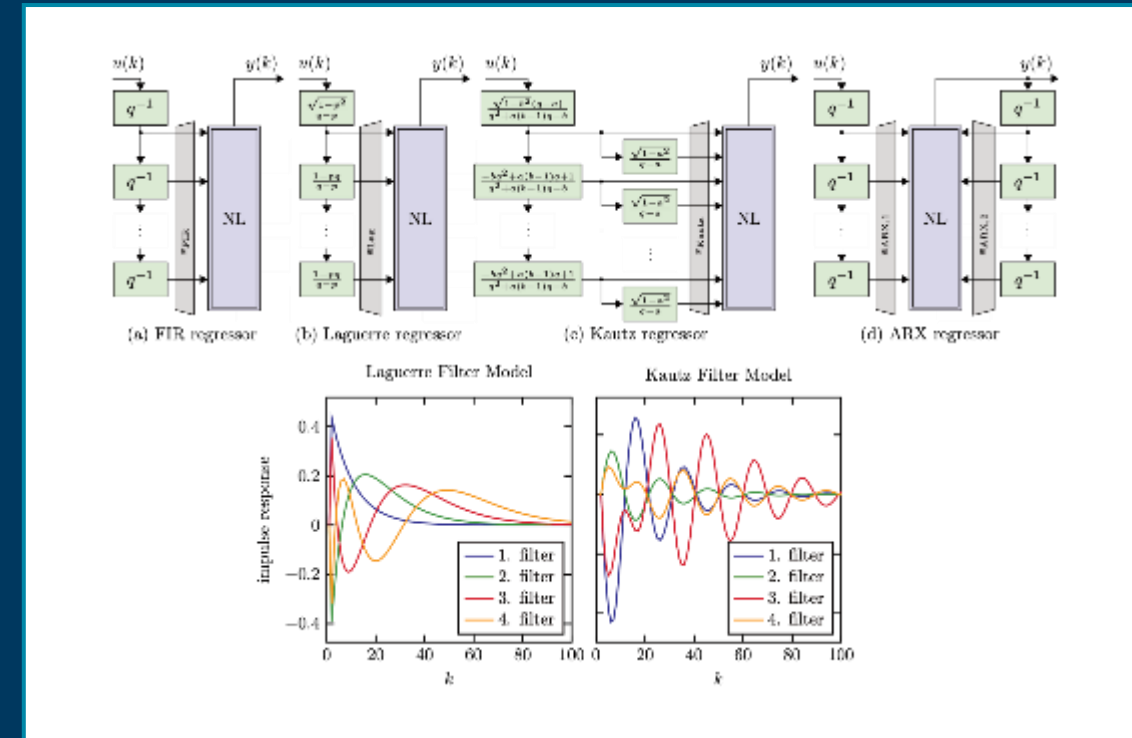
- Local Model Network consists of Many Local Linear/Affine Models
- Each Local Model represents an FIR Structure
- Specific Types of Regularization Incorporate Prior Knowledge
- Key Properties
 - inherently stable
 - gray-box
 - very robust w.r.t. model order and dead time
 - least squares estimation



Nonlinear System Identification

Nonlinear Laguerre and Kautz Models

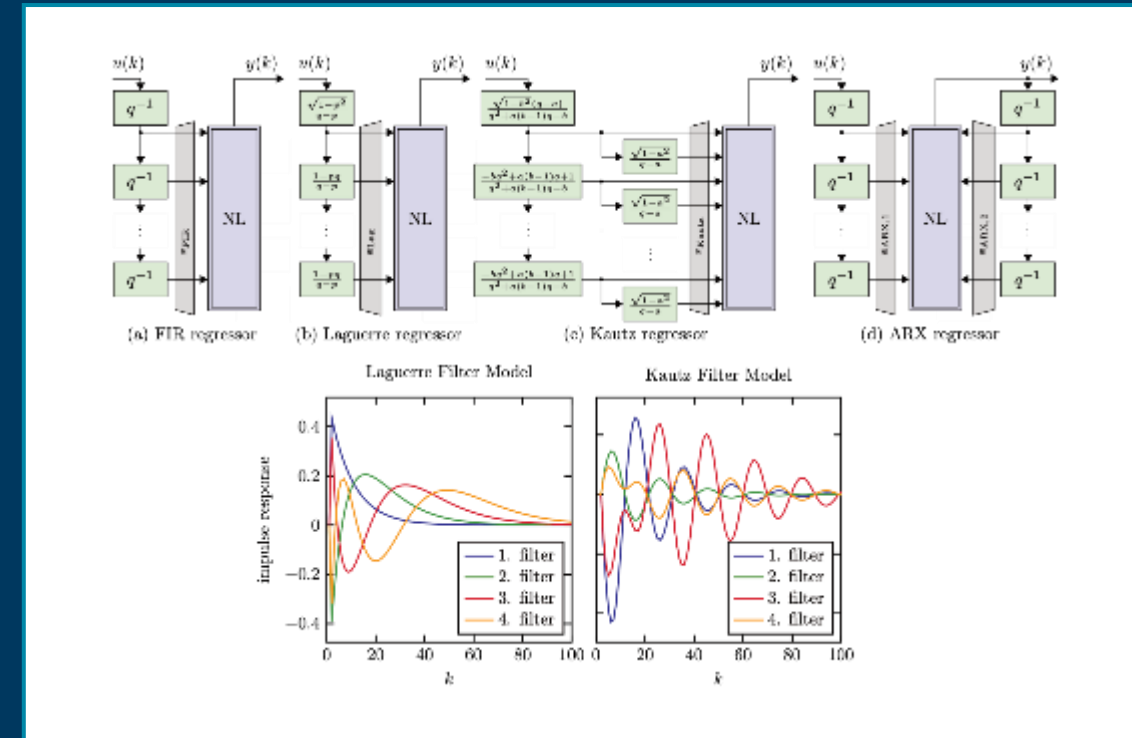
- Structured/Less Flexible Version of Regularized FIR
- Sparser than Regularized FIR
- Laguerre: Asymptotic Processes
- Kautz: Oscillatory Processes



Nonlinear System Identification

Nonlinear Laguerre and Kautz Models

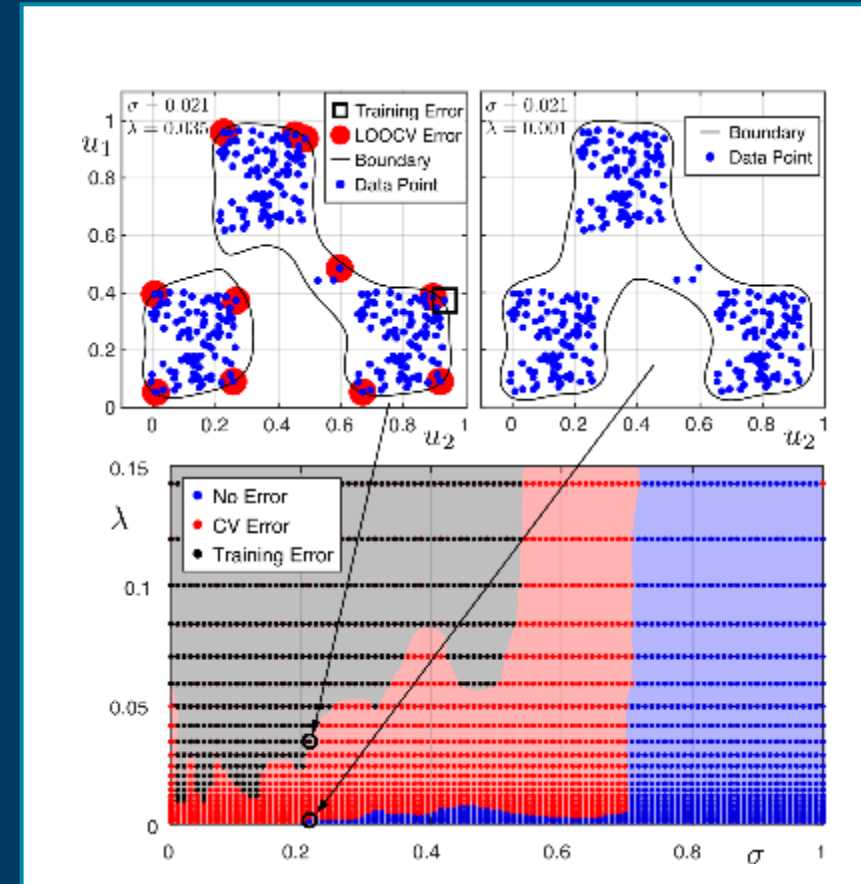
- Structured/Less Flexible Version of Regularized FIR
- Sparser than Regularized FIR
- Laguerre: Asymptotic Processes
- Kautz: Oscillatory Processes



Classification and Diagnosis

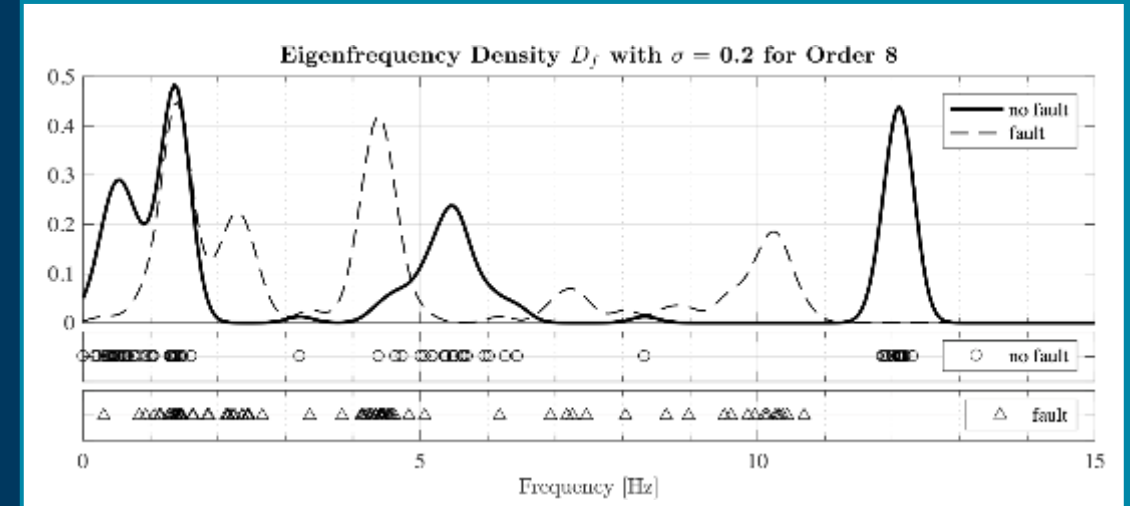
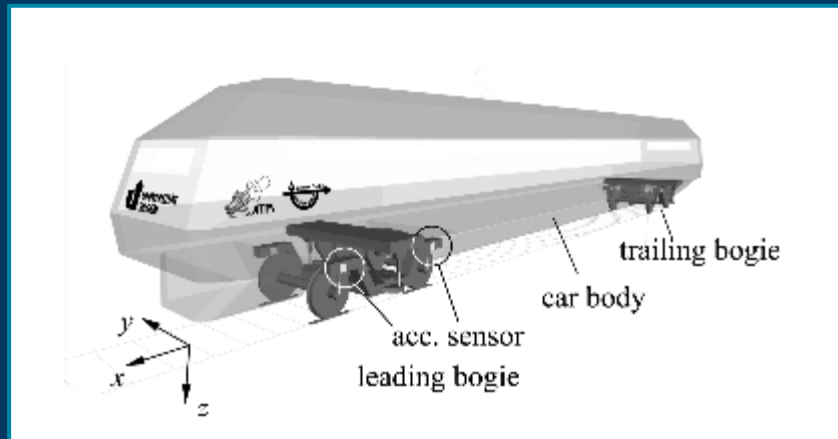
Robust One- and Two-Class Classifiers

- Robust Classification Boundaries via Zero Leave-One-Out Cross-Validation Errors
- Classifiers based on Least Squares Estimation: LS-SVM or GPs or RBF Networks
- Efficient Computation of Leave-One-Out (LOO) Error
- Hyperparameter Tuning by Optimization of LOO Error
- Hyperparameters: e.g. Length Scale σ and Regularization Strength λ
- Different Strategies for One- and Two-Class Classifiers



Structural Health Monitoring (SHM) Using Probability Density Estimation

- Time Series Subspace Identification → Eigenfrequencies
- Eigenfrequencies for Sequences → Density Estimation
- Density → Fault Diagnosis



Technical Thermodynamics

Prof Dr Thomas Seeger

ZESS Senior Speaker & Member of the Board



Forschungsschwerpunkte

- Verbrennungstechnik
- Turbulente Verbrennung
- Motorische Verbrennung, Brennverfahren
- Lasermesstechnik
- Effiziente Energienutzung
- Adsorptionstechnik
- Wärmeprozesse
- Optimierung von Strömungs-, Wärme- und Stofftransport
- Methoden der optischen Lasermesstechnik
 - Particle-Image-Velocimetry
 - Planare Laserinduzierte Fluoreszenz
 - Planare Rayleighstreuung
- Computational Fluid Dynamics (CFD)
- Berechnung von Strömung und Optimierung, Reaktion und Wärmetransport

Media Systems

Prof Dr Volker Blanz



- Computer Graphics
- Machine Vision
- Machine Learning
- Human Perception
- Learning-Based Modelling of Objects

$$E = \sum_{x,y} \| \mathbf{I}_{input}(x,y) - \mathbf{I}_{model}(x,y) \|^2$$

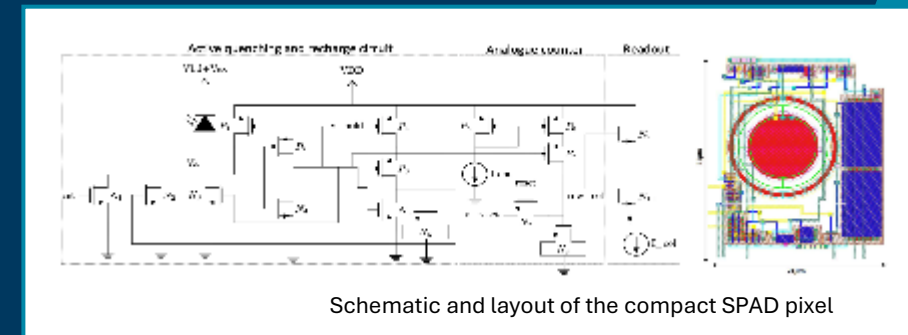
Integrated Analogue Circuits and Image Sensors

Prof Dr Bhaskar Choubey



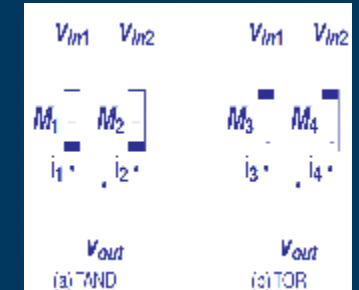
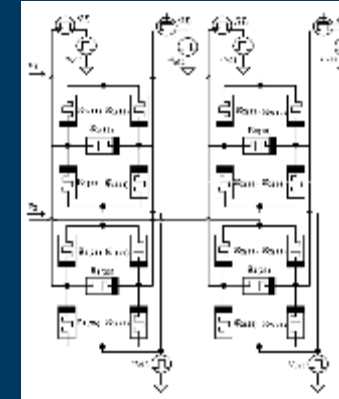
Skills

- CMOS Image Sensors
 - Wide dynamic range imaging
 - Single Photon Imaging
- Analogue and mixed signal chip design
 - Neural networks on chip
- Microelectromechanical resonant sensors

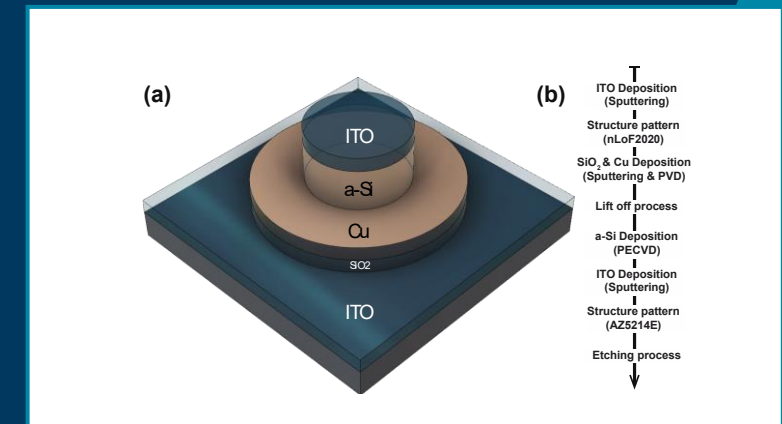


Current Work

- **Memristors and its integration with CMOS Circuits**
 - AI Accelerators
 - Analogue circuits using Memristors
 - Low power intelligent sensors for Edge
- **Intelligent image sensors**
 - New geometries, resolutions and image acquisition pathways
 - Surround view imaging systems
- **Single photon imaging**
 - UV imaging using silicon systems
 - Amorphous silicon and amorphous Germanium detectors
- **Learning in business processes**
 - Liquidity and credit management



The TAND gate and TOR gate



Production Automation and Assembly

Prof Dr Martin Manns



„Montage der Zukunft“

Robotik in der Produktion



Montage-Planung



Additive-Subtraktive Fertigung



HiSMoT



Flex4Res



Walzist

RoboPutz

Numerical Analysis

Prof Dr Thorsten Raasch



Forschungsschwerpunkte

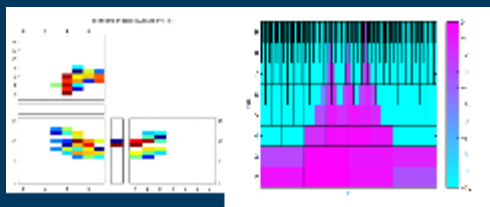
- Analysis numerischer Verfahren, insbes. Stabilität und Konvergenzuntersuchungen
- adaptive Finite Elemente und Wavelet Methoden
- Numerik inverser Probleme, insbes. bei Inverser Wärmeleitung, Parameteridentifizierung, Gebietsoptimierung
- singulär gestörte gewöhnliche und partielle Differentialgleichungen
- Approximationstheorie, Splines

Research Topics

Adaptive Discretization Methods

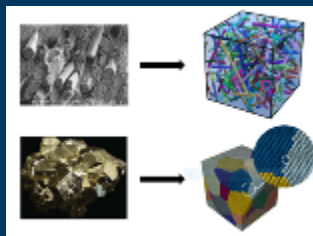
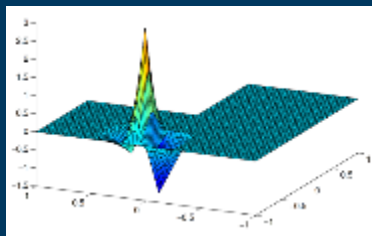
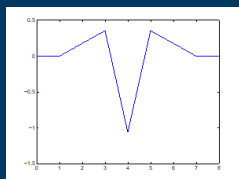
- A posteriori error estimation
- Convergence and complexity analysis
- e.g., adaptive FEM, wavelet and Fourier methods

$$\|u - u_{\Lambda^k}\| \approx ? \Rightarrow \begin{cases} \Lambda^{k+1} := ? \\ \#\Lambda^{k+1} \approx ? \end{cases}$$



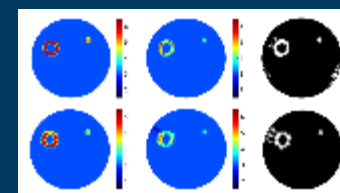
Numerical Fourier and Wavelet Methods

- Wavelet-based solvers for PDEs
- Hybrid schemes with redundant ansatz systems
- e.g., particle-continuum models, hp-FEM, quarklets



Numerical Solution of Inverse Problems

- Variational, Tikhonov-type regularization methods
- Nonsmooth, high-order numerical optimization
- e.g., smooth+nonsmooth functionals, bilevel problems

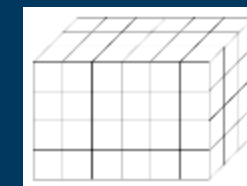
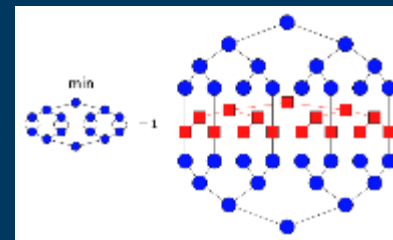


$$x \in \arg \min_{y \in H} f(y) + g(y)$$

$$\Leftrightarrow F(x) := x - \text{prox}_{tg}(x - t\nabla f(x)) = 0$$

Numerical Multilinear Algebra

- Large-scale, structured eigenvalue problems
- Tensor decomposition
- Tensor eigenvalue problems



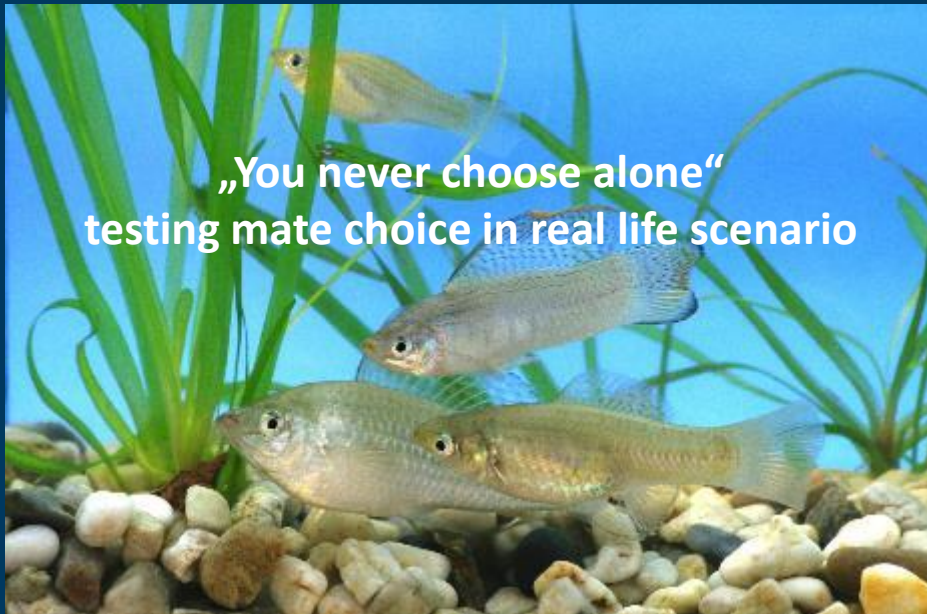
$$\mathcal{T} = \sum_{k=1}^r \lambda_k \mathbf{v}_k^{\otimes d}$$

Ecology and Behavioural Biology

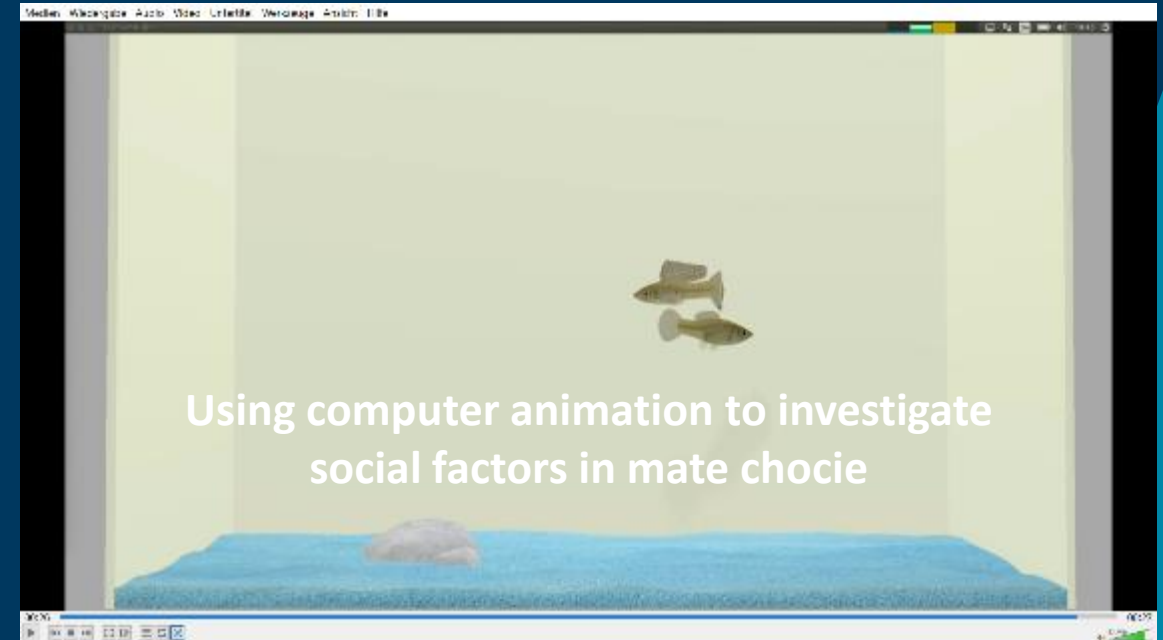
Prof Dr Klaudia Witte



Social factors in mate choice



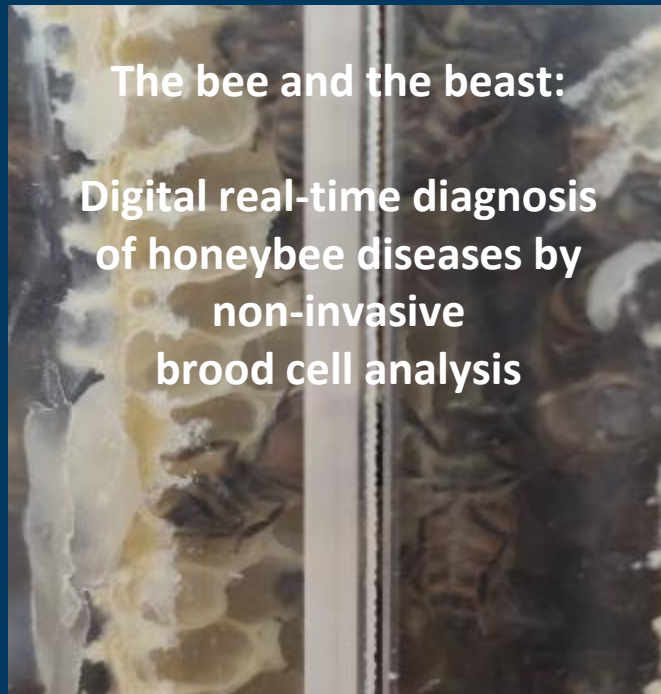
&



Social learning when foraging



Sensor Innovation to protect honeybees



AI in nature conservation

